# Multilinear Image Representation and Statistical Learning Models http://virtual01.Incc.br/~giraldi/Tutorial2016/ 

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## Topics

(1) Introduction to Multilinear Data Representation
(2) Dimensionality Reduction in Tensor Spaces.
(1) Generalized Matrix and Tensor Product Approaches
(3) Subspace Learning in Tensor Spaces: General Problem
(1) Multilinear Principal Component Analysis (MPCA) and Variants
(9) Discriminant Analysis and Recognition in Multilinear Spaces.
(5) Application: FEI Database Analysis.
(1) Implementation Details
(2) Ranking and Understanding Tensor Components
(3) Recognition Rates in Gender Experiments
(1) Tensor Components and Reconstruction
(0) Perspectives.
( Conclusions and Final Remarks.

## Introduction

Mathematical Representation and Analysis of Image Databases

- Redundancy
- High-dimensional spaces



## Introduction

Mathematical Representation and Analysis of Image Databases

- Redundancy
- High-dimensional spaces

- Linear Techniques:PCA
- Kernel Methods
- Multilinear Image Representation


## Introduction



$$
m \text {-dimensional }
$$

$$
m^{\prime}-\text { dimensional }
$$

$\Rightarrow$ Linear Dimensionality Reduction

$$
m^{\prime} \ll m
$$

$\Rightarrow$ Multilinear Dimensionality Reduction

## Introduction

Linear Techniques:PCA


$$
P_{p c a}=\arg \min _{P} \sum_{i=1}^{N}\left\|P \cdot I_{m^{\prime}} \cdot P^{T} \cdot \widetilde{x}_{i}-\widetilde{x}_{i}\right\|^{2} .
$$

(1) Consider a gray scale $m_{1} \times m_{2}$ image as a high dimensional vector in $\Re^{m}$ space, where $m=m_{1} \cdot m_{2}$.
(2) $\bar{x}=\frac{1}{N} \sum_{i=1}^{N} x_{i}$.
(9) $S=\sum_{i=1}^{N} \widetilde{x}_{i} \cdot \widetilde{x}_{i}^{T}$.
(3) $\widetilde{x}_{i}=x_{i}-\bar{x}$.
(0) $P^{T} S P=\Lambda$.

## Introduction

Details about PCA.


$$
\begin{gathered}
\mathbf{y}=P^{T} \mathbf{x} \\
P I_{m \prime} \mathbf{y}=P I_{m^{\prime}} P^{T} \mathbf{x} \\
\mathbf{x}^{R}=P I_{m \prime} \mathbf{y}=\sum_{j=1}^{m \prime} y_{j} \mathbf{p}_{j}
\end{gathered}
$$

Image $I \in \mathbb{R}^{m_{1} \times m_{2}}$ then:
$\mathbf{p}_{j} \in \mathbb{R}^{m_{1} \cdot m_{2}}$.

Naive Multiresolution using PCA.


## Limitations of PCA.

- Dimension of rows and column spaces in PCA system
- Dimensionality reduction means only truncate expression:

$$
\mathbf{x}=\sum_{j=1}^{m} y_{j} \mathbf{p}_{j}
$$

- Dimension of covariance matrix $S$ may be high
- Small sample size problem:
- We do not need to decompose $S$
- Limited number of dimensions


## Multidimensional Image Data Representation



Figure: Samples from FEI database. http://fei.edu.br/~cet/facedatabase.html

## Introduction

Multiliner Techniques: Tensor Representation

- Generalization of linear technique to dimensionality reduction.
- Generalized matrix for data representation: named tensor.

- Multilinear techniques as:

Images in gray scale: third order tensor
(1) Multilinear Principal Components Analysis (MPCA)[Lu et al., 2008].
(2) MPCA variants [Lu et al., 2009, Panagakis et al., 2010].
(3) Concurrent Subspace Analysis (CSA) [Xu et al., 2008]

## Applications for Multiliner Techniques

- Face transfer: use one face to animate another one [Vlasic et al., 2005],
- Face recognition/reconstruction under multiple viewpoints [Filisbino et al., 2013b, Jia and Gong, 2005],
- Video content representation and retrieval [Zhou et al., 2012, Liu et al., 2008],
- Gait recognition [Lu et al., 2008],
- Visualization and computer graphics [Pajarola et al., 2013].


## Applications: Face transfer: use one face to animate another one



Figure: Pose, identity, expressions, visemes (speech-related mouth articulations). Source [Vlasic et al., 2005]

Applications: Face reconstruction under multiple viewpoints

(a)

(b)

(c)

(d)

(e)

(f)

(g)

(h)

(i)

(j)

(k)

Figure: (a) Low-resolution $14 \times 9$. (b)-(f) Reconstruction in $56 \times 36$. (g)-(k) Ground truth. (source [Jia and Gong, 2005])

## Applications: Video content representation and retrieval



Figure: Find clips that are identical in content to a query (source [Zhou et al., 2012])

## Applications: Gait Recognition

## 



Figure: Third-order tensor representing a gait silhouette sequence (source [Lu et al., 2008]).

## Applications: Multiresolution Volume Visualization



Figure: Multiscale tensor reconstruction for visualization (source [Suter et al., 2011])

## Tensor Product Spaces

- Vector spaces $V_{1}$ and $V_{2} ; \operatorname{dim}\left(V_{1}\right)=n$ and $\operatorname{dim}\left(V_{2}\right)=m$,
- Basis: $\left\{\mathbf{e}_{1}^{1}, \mathbf{e}_{1}^{2}, \mathbf{e}_{1}^{3}, \ldots, \mathbf{e}_{1}^{n}\right\}$ and $\left\{\mathbf{e}_{2}^{1}, \mathbf{e}_{2}^{2}, \mathbf{e}_{2}^{3}, \ldots, \mathbf{e}_{2}^{m}\right\}$,
- Tensor product $V_{1} \otimes V_{2}$ :
(1) Dimension:

$$
\begin{equation*}
\operatorname{dim}\left(V_{1} \otimes V_{2}\right)=n . m \tag{1}
\end{equation*}
$$

(2) Basis:

$$
\begin{gather*}
V_{1} \otimes V_{2} \\
=\operatorname{span}\left\{\mathbf{e}_{1}^{i} \otimes \mathbf{e}_{2}^{j} ; 1 \leq i \leq n, 1 \leq j \leq m\right\}, \tag{2}
\end{gather*}
$$

(3) Given $\mathbf{v}=\sum_{i=1}^{n} v_{i} \mathbf{e}_{1}^{i}$ and $\mathbf{u}=\sum_{j=1}^{m} u_{j} \mathbf{j}_{2}^{j}$ :

$$
\begin{equation*}
\mathbf{v} \otimes \mathbf{u}=\sum_{i=1}^{n} \sum_{j=1}^{m} v_{i} u_{j} \mathbf{e}_{1}^{i} \otimes \mathbf{e}_{2}^{j} . \tag{3}
\end{equation*}
$$

## Generalizing Tensor Product Spaces

- Given $V_{1}, V_{2}, \ldots, V_{n}$, with $\operatorname{dim}\left(V_{i}\right)=m_{i}$, and $\left\{\mathbf{e}_{i}^{1}, \mathbf{e}_{i}^{2}, \ldots, \mathbf{e}_{i}^{m_{i}}\right\}$ a basis for $V_{i}$, then:

$$
\begin{gather*}
V_{1} \otimes V_{2} \otimes \ldots \otimes V_{n} \\
=\operatorname{span}\left\{\mathbf{e}_{1}^{i_{1}} \otimes \mathbf{e}_{2}^{i_{2}} \otimes \ldots \otimes \mathbf{e}_{n}^{i_{n}} ; \mathbf{e}_{k}^{i_{k}} \in V_{k}\right\}, \tag{4}
\end{gather*}
$$

- A tensor $\mathbf{X}$ of order $n$ is an element $\mathbf{X} \in V_{1} \otimes V_{2} \otimes \ldots \otimes V_{n}$ :

$$
\begin{equation*}
\mathbf{X}=\sum_{i_{1}, i_{2}, \cdots, i_{n}} \mathbf{X}_{i_{1}, i_{2}, \cdots, i_{n}} \mathbf{e}_{1}^{i_{1}} \otimes \mathbf{e}_{2}^{i_{2}} \otimes \cdots \otimes \mathbf{e}_{n}^{i_{n}} \tag{5}
\end{equation*}
$$

## Changing Tensor Representation

- Let $V_{i}=\mathbb{R}^{m_{i}}$ and new basis:

$$
\begin{equation*}
\widetilde{B}=\left\{\widetilde{\mathbf{e}}_{1}^{i_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{i_{2}} \otimes \cdots \otimes \widetilde{\mathbf{e}}_{n}^{i_{n}}, \quad \widetilde{\mathbf{e}}_{k}^{i_{k}} \in \mathbb{R}^{m_{k}}\right\} \tag{6}
\end{equation*}
$$

- Basis change matrices $R^{k} \in \mathbb{R}^{m_{k} \times m_{k}}$, defined by:

$$
\begin{equation*}
\mathbf{e}_{k}^{i_{k}}=\sum_{j_{k}=1}^{m_{k}} R_{i_{k} j_{k}}^{k} \widetilde{\mathbf{e}}_{k}^{j_{k}}, \tag{7}
\end{equation*}
$$

where $k=1,2, \cdots, n$ and $i_{k}=1,2, \cdots, m_{k}$.

- New tensor representation:

$$
\begin{equation*}
\mathbf{X}=\sum_{j_{1}, j_{2}, \cdots, j_{n}} \widetilde{\mathbf{X}}_{j_{1}, j_{2}, \cdots, j_{n}} \widetilde{\mathbf{e}}_{1}^{j_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{j_{2}} \cdots \otimes \widetilde{\mathbf{e}}_{n}^{j_{n}}, \tag{8}
\end{equation*}
$$

with:

$$
\widetilde{\mathbf{X}}_{j_{1}, j_{2}, \cdots, j_{n}}=\sum_{i_{1}, i_{2}, \cdots, i_{n}} \mathbf{X}_{i_{1}, i_{2}, \cdots, i_{n}} R_{i_{1} j_{1}}^{1} R_{i_{2} j_{2}}^{2} \ldots R_{i_{n} j_{n}}^{n}
$$

## Dimensionality Reduction in Tensor Spaces

- Projection matrices $U^{k} \in \mathbb{R}^{m_{k} \times m /_{k}}$, as follows:

$$
\begin{equation*}
U_{i_{k} j_{k}}^{k}=R_{i_{k} j_{k}}^{k}, \quad i_{k}=1,2, \cdots, m_{k} ; \quad j_{k}=1,2, \cdots, m \prime_{k} \tag{9}
\end{equation*}
$$

with $k=1,2, \cdots, n, m_{k} \leq m_{k}$.

- Reduced representation:

$$
\begin{equation*}
\mathbf{Y}=\sum_{j_{1}, j_{2}, \cdots, j_{n}=1}^{m /_{1}, \cdots, m / n} \mathbf{Y}_{j_{1}, j_{2}, \cdots, j_{n}} \widetilde{\mathbf{e}}_{1}^{j_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{j_{2}} \cdots \otimes \widetilde{\mathbf{e}}_{n}^{j_{n}}, \tag{10}
\end{equation*}
$$

where:

$$
\begin{equation*}
\mathbf{Y}_{j_{1}, j_{2}, \cdots, j_{n}}=\sum_{i_{1}, i_{2}, \cdots, i_{n}=1}^{m_{1}, \cdots, m_{n}} \mathbf{X}_{i_{1}, i_{2}, \cdots, i_{n}} U_{i_{1} j_{1}}^{1} U_{i_{2} j_{2}}^{2} \ldots U_{i_{n} j_{n}}^{n} . \tag{11}
\end{equation*}
$$

## Tensor Product Formalism

- Advantage: clarify tensor operations
- Disadvantage: uncomfortable expressions. Example:

$$
\begin{equation*}
\mathbf{Y}=\sum_{j_{1}, j_{2}, \cdots, j_{n}=1}^{m / 1, \cdots, m \prime_{n}} \mathbf{Y}_{j_{1}, j_{2}, \cdots, j_{n}} \widetilde{\mathbf{e}}_{1}^{j_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{\tilde{j}_{2}} \cdots \otimes \widetilde{\mathbf{e}}_{n}^{j_{n}} \tag{12}
\end{equation*}
$$

- Solution: Generalized matrix approach:

$$
\begin{equation*}
\mathbf{Y}=\left[\mathbf{Y}_{j_{1}, j_{2}, \cdots, j_{n}}\right]_{j_{1},,_{2}, \cdots, j_{n}=1}^{m_{1}, \cdots, m / n} \tag{13}
\end{equation*}
$$

- Multilinear functions/algebra and generalized matrices


## Generalized Matrix Approach

- A tensor $\mathbf{X}$ in expression (5) is just a generalized matrix $\mathbf{X} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}$,
- The mode-k product of tensor $\mathbf{X} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}$ with the matrix $A \in \mathbb{R}^{m / k \times m_{k}}$ is given by:

$$
\left(\mathbf{X} \times_{k} A\right)_{i_{1}, \ldots, i_{k-1}, i, i_{k+1}, \ldots, i_{n}}
$$

$$
\begin{equation*}
=\sum_{j=1}^{m_{k}} \mathbf{X}_{i_{1}, \ldots, i_{k-1}, j, i_{k+1}, \cdots i_{n}} A_{i, j}, \quad i=1,2, \ldots, m \prime_{k} \tag{14}
\end{equation*}
$$

## Generalized Matrix Approach

- Dimensionality Reduction: We can compute expression (11) as:

$$
\begin{equation*}
\mathbf{Y}_{j_{1}, j_{2}, \cdots, j_{n}}=\left(\mathbf{X} \times 1 U^{1^{T}} \times{ }_{2} U^{2^{T}} \ldots \times_{n} U^{n^{T}}\right)_{j_{1}, j_{2}, \cdots, j_{n}} \tag{15}
\end{equation*}
$$

or, in a compact form [Filisbino et al., 2013a]:

$$
\begin{equation*}
\mathbf{Y}=\mathbf{X} \times_{1} U^{1^{T}} \times_{2} U^{2^{T}} \ldots \times_{n} U^{n^{T}} \tag{16}
\end{equation*}
$$

- Reconstruction:

$$
\begin{equation*}
\mathbf{X}^{R}=\mathbf{Y} \times_{1} U^{1} \ldots \times_{n} U^{n}, \tag{17}
\end{equation*}
$$

- 

$$
\begin{equation*}
\mathbf{X}^{R}=\mathbf{X} \times_{1} U^{1} U^{1^{T}} \ldots \times_{n} U^{n} U^{n^{T}}, \tag{18}
\end{equation*}
$$

## Multilinear Spaces: Definitions

$\Rightarrow$ A tensor of order $n$ is just a generalized matrix $\mathbf{X} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}$.
Then:
(1) There is an isomorphism between $\mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}$ and $\mathbb{R}^{m_{1} \cdot m_{2} \cdots m_{n}}$.
(2) The internal product between two tensors $\mathbf{X} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}$ and $\mathbf{Y} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}$ is defined by:

$$
\langle\mathbf{X}, \mathbf{Y}\rangle=\sum_{i_{1}=1, \ldots, i_{n}=1}^{m_{1}, \ldots, m_{n}} \mathbf{X}_{i_{1}, . ., i_{n}} \mathbf{Y}_{i_{1}, . ., i_{n}}
$$

(3) The Frobenius norm of a tensor is given by the expression: $\|\mathbf{X}\|=\sqrt{\langle\mathbf{X}, \mathbf{X}\rangle}$, and the distance between tensors $\mathbf{X}$ and $\mathbf{Y}$ is computed by:

$$
D(\mathbf{X}, \mathbf{Y})=\|\mathbf{X}-\mathbf{Y}\|
$$

## Multilinear Spaces: Terminology

(1) Tensor of order $n$;
(2) Mode $k$
(3) Tensor components

$$
\begin{equation*}
\widetilde{\mathbf{e}}_{1}^{j_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{j_{2}} \cdots \otimes \widetilde{\mathbf{e}}_{n}^{j_{n}} \tag{19}
\end{equation*}
$$

(9) Core Tensor $\mathbf{Y}$ :

$$
\begin{equation*}
\mathbf{X}^{R}=\mathbf{Y} \times_{1} U^{1} \ldots \times_{n} U^{n} \tag{20}
\end{equation*}
$$

(5) Tensor Fields
(6) Multilinear versus Tensor
(3) Component space: $V_{i}$ in expression

$$
V_{1} \otimes V_{2} \otimes \ldots \otimes V_{n}
$$

or $\mathbb{R}^{m_{i}}$ in expression

$$
\mathbb{R}^{m_{1}} \otimes \mathbb{R}^{m_{2}} \otimes \ldots \otimes \mathbb{R}^{m_{n}} \equiv \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}
$$

## Multilinear Dimensionality Reduction



Original $\mathbb{R}^{m_{1} \times m_{2} \times m_{3}}$
image:


Projected images:

$$
\mathbb{R}^{m_{1}^{\prime} \times m_{2}^{\prime} \times m_{3}^{\prime}}
$$



Reconstruction visualization: $\mathbb{R}^{m_{1} \times m_{2} \times m_{3}}$

Problem: Optimality criteria to seek for suitable matrices $U^{1}, U^{2}, \ldots, U^{n}$.

## Concurrent Subspace Analysis (CSA)

- Database: $D=\left\{\mathbf{X}_{i} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}, i=1,2, \ldots, N\right\}$
- Least square error minimization criterium:

$$
\left(\left.U^{j}\right|_{j=1} ^{n}\right)=\arg \min _{\left.U j\right|_{j=1} ^{n}} \sum_{i=1}^{N}\left\|\mathbf{X}_{i} \times_{1} U^{1} U^{1^{T}} \ldots \times_{n} U^{n} U^{n^{T}}-\mathbf{X}_{i}\right\|^{2}
$$

We can re-write CSA problem as follows:

$$
\begin{equation*}
P^{\star}=\arg \min _{P} \sum_{i=1}^{N}\left\|P P^{T} x_{i}^{v}-x_{i}^{v}\right\|^{2} \tag{21}
\end{equation*}
$$

subject to :

$$
\begin{equation*}
P=U^{n} \otimes U^{n-1} \otimes \ldots \otimes U^{1} \tag{22}
\end{equation*}
$$

so, CSA is a constrained version of PCA [Filisbino et al., 2013a].

## Analysis of Constrained PCA

- Simplified Version:

$$
\begin{equation*}
P^{\star}=\arg \min _{P} \sum_{i=1}^{N}\left\|P I_{m} P^{T} x_{i}^{v}-x_{i}^{v}\right\|^{2} \tag{23}
\end{equation*}
$$

subject to :

$$
\begin{equation*}
P=C \otimes D, \tag{24}
\end{equation*}
$$

- A simple manipulation shows that we must maximize [Filisbino et al., 2013a]:

$$
\widetilde{J_{m}}=\operatorname{Tr}\left[I_{m} P^{T} R P\right],
$$

## Analysis of Constrained PCA

- Lagrange multipliers:

$$
\begin{aligned}
& \widetilde{J_{m}}=\operatorname{Tr}\left[I_{m}(C \otimes D)^{T} R(C \otimes D)\right] \\
+ & \operatorname{Tr}\left[I_{m}\left(I-(C \otimes D)^{T}(C \otimes D)\right) M\right],
\end{aligned}
$$

- Gateux derivative respect to the $C$ [Filisbino et al., 2013a]:

$$
\lim _{\tau \rightarrow 0} \frac{\widetilde{J_{m}}(C+\tau H)-\widetilde{J_{m}}(C)}{\tau}=0,
$$

- If $C \in \mathbb{R}^{s \times s}$ :

$$
N_{\text {equations }}=s^{2}+s+1 \text {, }
$$

equations against $2 s^{2}$ variables

## Mode-k Flattening and CSA



Figure: Mode-k Flattening to convert tensor into matrix

## CSA Fundamental Theorem

## Theorem

If $\left(U^{1}, \ldots, U^{k-1}, U^{k+1}, \ldots, U^{n}\right)$ are known then the matrix $U^{k}$ ideal is composed by the $m{ }^{\prime}{ }_{k}$ principal eigenvectors of the covariance matrix

$$
C^{(k)}=\sum_{i=1}^{N} X_{i(k)}^{k} X_{i(k)}^{k^{T}}
$$

where $X_{i(k)}^{k}$ is the matrix generated through the mode-k flattening of the $\mathbf{X}_{i}^{k}$; that is:

$$
X_{i(k)}^{k} \Longleftarrow{ }_{k} \mathbf{X}_{i}^{k},
$$

and

$$
\mathbf{X}_{i}^{k}=\mathbf{X}_{i} \times_{1} U^{1^{T}} \ldots \times_{k-1} U^{k-1^{T}} \times_{k+1} U^{k+1^{T}} \ldots \times_{n} U^{n^{T}}
$$

## Multilinear Principal Component Analysis (MPCA)

- Let us consider a database:

$$
\begin{equation*}
D=\left\{\mathbf{X}_{i} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}, i=1,2, \ldots, N\right\} \tag{25}
\end{equation*}
$$

- Variance maximization [Lu et al., 2008]:

$$
\begin{equation*}
\left(\left.U^{j}\right|_{j=1} ^{n}\right)=\arg \max _{\left.U^{j}\right|_{j=1} ^{n}} \frac{1}{N} \sum_{i=1}^{N}\left\|\mathbf{Y}_{i}-\overline{\mathbf{Y}}\right\|^{2}, \tag{26}
\end{equation*}
$$

where $\mathbf{Y}_{i}$ is given by expression (16) and $\overline{\mathbf{Y}}$ is the mean tensor computed by:

$$
\begin{equation*}
\overline{\mathbf{Y}}=\frac{1}{N} \sum_{i=1}^{N} \mathbf{Y}_{i} \tag{27}
\end{equation*}
$$

## Multilinear Principal Component Analysis

- Theorem: Let $U^{k} \in \mathbb{R}^{m_{k} \times m^{\prime}}{ }^{\prime} i=1,2, \ldots, n$, be the solution to (26). Then, given the projection matrices $U^{1}, \ldots, U^{k-1}, U^{k+1}, \ldots, U^{n}$, the matrix $U^{k}$ consists of the $m{ }^{\prime}{ }_{k}$ principal eigenvectors of the matrix:

$$
\begin{equation*}
\Phi^{(k)}=\sum_{i=1}^{N}\left(X_{i(k)}-\bar{X}_{(k)}\right) U_{\Phi(k)} \cdot U_{\Phi(k)}^{T} \cdot\left(X_{i(k)}-\bar{X}_{(k)}\right)^{T} \tag{28}
\end{equation*}
$$

where $X_{i(k)}$ and $\bar{X}_{(k)}$ are the mode-k flattening of sample tensor $X_{i}$ and of the global mean $\bar{X}$, respectively, and:

$$
\begin{equation*}
U_{\Phi(k)}=U^{k+1} \otimes U^{k+2} \otimes \ldots \otimes U^{n} \otimes U^{1} \otimes U^{2} \otimes \ldots \otimes U^{k-1} \tag{29}
\end{equation*}
$$

## Proof of MPCA Theorem [Lu et al., 2008]

Properties: $\|\mathbf{X}\|=\left\|X_{(k)}\right\|,\|A\|^{2}=\operatorname{trace}\left(A A^{T}\right)$ and, if
$\mathbf{S}=\mathbf{X} \times{ }_{1} U^{1} \times_{2} U^{2} \ldots \times_{n} U^{n}$ then $S_{(k)}=U^{k} X_{(k)}\left(U_{\Phi}(k)\right)^{T}$, where $U_{\Phi^{(k)}}$ is given by (29),

$$
\begin{gathered}
\Psi=\sum_{i=1}^{N}\left\|\mathbf{Y}_{i}-\overline{\mathbf{Y}}\right\|^{2}=\sum_{i=1}^{N}\left\|\left(\mathbf{X}_{i}-\overline{\mathbf{X}}\right) \times_{1} U^{1^{\top}} \times_{2} U^{2^{\top}} \ldots x_{n} U^{n^{\top}}\right\|^{2} \\
=\sum_{i=1}^{N}\left\|U^{k^{\top}}\left(X_{i(k)}-\bar{X}_{(k)}\right) U_{\Phi(k)}\right\|^{2}
\end{gathered}
$$

## Proof of MPCA Theorem (Continue)

$$
\begin{gathered}
=\sum_{i=1}^{N} \operatorname{trace}\left(U^{k^{T}}\left(X_{i(k)}-\bar{X}_{(k)}\right) U_{\Phi(k)} \cdot U_{\Phi(k)}^{T}\left(X_{i(k)}-\bar{X}_{(k)}\right)^{T} U^{k}\right) \\
\operatorname{trace}\left(U^{k^{T}} \sum_{i=1}^{N}\left[\left(X_{i(k)}-\bar{X}_{(k)}\right) U_{\Phi(k)} \cdot U_{\Phi(k)}^{T}\left(X_{i(k)}-\bar{X}_{(k)}\right)^{T}\right] U^{k}\right) \\
=\operatorname{trace}\left(U^{k^{T}} \Phi^{(k)} U^{k}\right) \\
\Phi^{(k)}=\sum_{i=1}^{N}\left(X_{i(k)}-\bar{X}_{(k)}\right) U_{\Phi(k)} \cdot U_{\Phi(k)}^{T} \cdot\left(X_{i(k)}-\bar{X}_{(k)}\right)^{T},
\end{gathered}
$$

## CSA/MPCA Equivalence

Theorem
If CSA receives centered input samples and $m_{k}=m \prime_{k}, k=1,2, \cdots, n$, then the obtained projection matrices $U^{1}, \ldots, U^{n}$ are equal to the ones generated by MPCA.

Proof. [Filisbino et al., 2015]

## MPCA and Traditional PCA

Considering tensors of order $n=1$. Input samples are vectors $x_{i} \in \mathbb{R}^{m_{1}}$, $i=1,2, \ldots, N$ and, in this case, we have only one projection matrix $U^{1} \in$ $\mathbb{R}^{m_{1} \times m /_{1}}$. If we consider full projection $\left(m \prime_{1}=m_{1}\right)$ then $U_{1}$ is an orthogonal matrix. Also, $\widetilde{y}_{i}=\widetilde{x}_{i} \times_{1} U^{1}=U^{1^{\top}} \widetilde{x}_{i}, \widetilde{x}_{i(k)} \rightarrow \widetilde{x}_{i}$ once we have just one mode $k=1$ in this case. Therefore, the matrix $\Phi^{(k)}$ assumes the form:

$$
\Phi^{(k)}=\phi^{(1)}=\sum_{i=1}^{N} \widetilde{x}_{i} \widetilde{x}_{i}^{T}=\sum_{i=1}^{N}\left(x_{i}-\bar{x}\right)\left(x_{i}-\bar{x}\right)^{T},
$$

which is the covariance matrix $S$ of the PCA.

## Tensor versus Linear Subspace Learning

- PCA.
- Vectorize the samples to get vectors $v \in \mathbb{R}^{m_{1} \cdot m_{2} \ldots m_{n}}$
- Covariance matrix $C \in \mathbb{R}^{m_{1} \cdot m_{2} \ldots m_{n} \times m_{1} \cdot m_{2} \ldots m_{n}}$
- Small sample size problems: $N \ll m_{1} \cdot m_{2} \ldots m_{n}$
- PCA:
- Number of PCA components is $(N-1)$ or less
- Efficient methods for PCA computation
- MPCA:
- Covariance matrices $C^{k} \in \mathbb{R}^{m_{k} \times m_{k}}$
- In general $N \cdot \amalg_{i \neq k} m_{i} \gg m_{k}$
- Flattening operation generates a number of $N \cdot \amalg_{i \neq k} m_{i}$ samples for $\phi^{(k)}$ computation


## Subspace Learning: Uncorrelated MPCA

Let the tensor-to-vector decomposition:

$$
\begin{equation*}
\mathbf{Y}_{i}=\sum_{p=1}^{P} y_{i_{p}} \widetilde{\mathbf{e}}_{p}^{1} \otimes \widetilde{\mathbf{e}}_{p}^{2} \cdots \otimes \widetilde{\mathbf{e}}_{p}^{n}, \quad P<\prod_{k=1}^{n} m_{k} \tag{30}
\end{equation*}
$$

Let:

$$
\bar{y}_{p}=\frac{1}{N} \sum_{i} y_{i_{p}}, \quad \mathbf{g}_{p}=\left(\begin{array}{llll}
y_{1_{p}} & y_{2_{p}} & \cdots & y_{N_{p}}
\end{array}\right)^{T} .
$$

Then:

$$
\begin{equation*}
\left(\widetilde{\mathbf{e}}_{p}^{1}, \widetilde{\mathbf{e}}_{p}^{2}, \ldots, \widetilde{\mathbf{e}}_{p}^{n}\right)=\arg \max \sum_{i=1}^{N}\left(y_{i_{p}}-\bar{y}_{p}\right)^{2}, \tag{31}
\end{equation*}
$$

subject to:

$$
\widetilde{\mathbf{e}}_{p}^{j} \cdot \widetilde{\mathbf{e}}_{p}^{j}=1, \quad \text { and } \quad \frac{\mathbf{g}_{p} \cdot \mathbf{g}_{q}}{\left\|\mathbf{g}_{p}\right\| \cdot\left\|\mathbf{g}_{q}\right\|}=\delta_{p q} .
$$

## Subspace Learning: Non-Negative MPCA

Problem

$$
\begin{equation*}
\left(\left.U^{j}\right|_{j=1} ^{n}\right)=\arg \max _{\left.U j\right|_{j=1} ^{n}} \frac{1}{N} \sum_{i=1}^{N}\left\|\mathbf{Y}_{i}-\overline{\mathbf{Y}}\right\|^{2}, \tag{32}
\end{equation*}
$$

subject to $U^{j} \geq 0$.
Solution [Panagakis et al., 2010]:

$$
\begin{equation*}
\left(\left.U^{j}\right|_{j=1} ^{n}\right)=\arg \max _{\left.U j\right|_{j=1} ^{n}} \frac{1}{N} \sum_{i=1}^{N}\left\|\mathbf{Y}_{i}-\overline{\mathbf{Y}}\right\|^{2}, \tag{33}
\end{equation*}
$$

subject to:

$$
U^{j} \in \operatorname{Gr}\left(m_{j}, m \prime_{j}\right) \quad \text { and } \quad U^{j} \geq 0
$$

where $\operatorname{Gr}\left(m_{j}, m_{j}\right)$ is the set of $m^{\prime}{ }_{j}$-dimensional linear subspaces of $\mathbb{R}^{m_{j}}$, termed the Grassmann manifold.

## Discriminant Analysis and Statistical Learning Approaches

## Dimensionality Reduction $\times$ Discriminant Analysis



Figure: (a) Scatter plot and principal directions. (b) The same population but distinguishing patterns plus $(+$ ) and triangle ( $\mathbf{\nabla}$ ).

## Discriminant Analysis and Classification

$\Rightarrow$ Find discriminate directions to separate sample groups
$\Rightarrow$ Classification approaches.

Supervised statistical learning methods like:

- Support Vector Machine (SVM)
- Discriminant Analsysis:

Linear: Linear Discriminant Analysis (LDA).
Multilinear: Fisher criterion [Lu et al., 2008].

## Support Vector Machine

SVM

- $f(x)=\left(x \cdot w^{s v m}\right)+b=0$
- $w^{\text {svm }}=\sum_{i=1}^{N} \alpha_{i} y_{i} x_{i}$



## Linear Discriminant Analysis

LDA

- $W^{\prime d a}=\underset{W}{\arg \max } \frac{\left|W^{T} S_{b} W\right|}{\left|W^{T} S_{w} W\right|}$.
- $S_{b}$ is the between-class matrix.
- $S_{w}$ is the within-class

$$
\begin{aligned}
& \Rightarrow S_{b}=\sum_{i=1}^{g} N_{i}\left(\bar{x}_{i}-\bar{x}\right)\left(\bar{x}_{i}-\bar{x}\right)^{T} \\
& \Rightarrow S_{w}= \\
& \sum_{i=1}^{g} \sum_{j=1}^{N_{i}}\left(x_{i, j}-\bar{x}_{i}\right)\left(x_{i, j}-\bar{x}_{i}\right)^{T}
\end{aligned}
$$

- $W_{\text {lda }}$ is eigenvectors of $S_{w}^{-1} S_{b}$.


## Linear Discriminant Analysis



## Ranking Tensor Components

- Total scatter tensor
- Estimating Spectral Structure of Data
- Tensor Discriminant Principal Component Analysis
- Fisher Discriminability Criterion


## Estimating Variances

- There is no a closed-form solution for subspace learning problems in tensor spaces.
- Total scatter tensor defined by [Lu et al., 2008]:

$$
\begin{equation*}
\boldsymbol{\Psi}_{j_{1}, j_{2}, \cdots, j_{n}}=\sum_{i=1}^{N} \frac{\left(\mathbf{Y}_{i ; j_{1}, j_{2}, \cdots, j_{n}-} \overline{\mathbf{Y}}_{j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}}{N}, \tag{34}
\end{equation*}
$$

- Rank the tensor components by sorting:

$$
\begin{equation*}
E=\left\{\boldsymbol{\Psi}_{j_{1}, j_{2}, \cdots, j_{n}}, j_{k}=1,2, \cdots, m_{k}\right\} \tag{35}
\end{equation*}
$$

## Spectral Structure of MPCA/CSA Subspaces

- Each component subspace:

$$
\left\{\widetilde{\mathbf{e}}_{k}^{j_{k}}, \quad j_{k}=1,2, \cdots, m^{\prime} k\right\}, \quad k=1,2, \cdots, n,
$$

has associated eigenvalues:

$$
\left\{\lambda_{j_{k}}^{k}, \quad j_{k}=1,2, \cdots, m \prime_{k}\right\}, \quad k=1,2, \cdots, n,
$$

- The data distribution in each subspace:

$$
\mathbf{v}_{k}=\sum_{j_{k}=1}^{m \prime_{k}} \lambda_{j_{k}}^{k} \tilde{j}_{k}^{j_{k}}, \quad k=1,2, \cdots, n,
$$

## Spectral Structure of MPCA Subspaces

- Variance explained by the element of basis $\widetilde{B}$ :

$$
\begin{gather*}
\mathbf{v}_{1} \otimes \mathbf{v}_{2} \otimes \cdots \otimes \mathbf{v}_{n} \\
=\sum_{j_{1}, j_{2}, \cdots, j_{n}} \lambda_{j_{1}}^{1} \lambda_{j_{2}}^{2} \cdots \lambda_{j_{n}}^{n} \widetilde{\mathbf{e}}_{1}^{j_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{j_{2}} \otimes \cdots \otimes \widetilde{\mathbf{e}}_{n}^{j_{n}} . \tag{36}
\end{gather*}
$$

- Consequently, we can rank the MPCA/CSA tensor components by sorting:

$$
\begin{equation*}
E=\left\{\lambda_{j_{1}, j_{2}, \cdots, j_{n}}=\lambda_{j_{1}}^{1} \lambda_{j_{2}}^{2} \cdots \lambda_{j_{n}}^{n}, j_{k}=1,2, \cdots, m_{k}\right\} . \tag{37}
\end{equation*}
$$

## Geometry Behind Discriminant Principal Components

 [Thomaz and Giraldi, 2010]

## Tensor Discriminant Principal Components - TDPCA

Tensor discriminant principal components analysis (TDPCA)
[Thomaz and Giraldi, 2010, Filisbino et al., 2015].
Steps:
(1) $\left\{\left(\mathbf{X}_{i}, l_{i}\right) ; \mathbf{X}_{i} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}, l_{i} \in\{-1,1\}, i=1,2, \ldots, N\right\}$
(2) Dimensionality reduction using the MPCA/CSA subspaces:

$$
\mathbf{Y}_{i} \in \mathbb{R}^{\left.m / 1_{1} \times m / 2 \times \ldots \times m\right)_{n}} .
$$

(3) Linear classifier is estimated using $\mathbf{Y}_{\mathbf{i}}$ and labels.

Separating hyperplane is defined through a discriminant tensor $\mathbf{W} \in \mathbb{R}^{m / 1 \times m / 2 \times \ldots \times m / n}$

We select the first principal MPCA/CSA components the ones with the highest discriminant weights, that is, $P_{\text {classifier }}=\left[p_{1}, p_{2}, \ldots, p_{m}\right]$, corresponding to the largest discriminant weights $\left|w_{1}\right| \geq\left|w_{2}\right| \geq \ldots \geq\left|w_{m}\right|$

## Fisher criterion [Lu et al., 2008]

$$
\begin{equation*}
W_{j_{1}, j_{2}, \cdots, j_{n}}^{F i j_{n}}=\frac{\sum_{c=1}^{C} N_{c} \cdot\left(\overline{\mathbf{Y}}_{c, j, j_{1}, j_{2}, \cdots, j_{n}} \overline{\mathbf{Y}}_{j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}}{\sum_{i=1}^{N}\left(\mathbf{Y}_{i ; j_{1}, j_{2}, \cdots, \cdots, j_{n}-} \overline{\mathbf{Y}}_{c_{i, j 1}, j_{2}, \cdots, \cdots, j_{n}}\right)^{2}} \tag{38}
\end{equation*}
$$

where,

- $C$ is the number of classes;
- $N_{c}$ is the number of elements of class $c$;
- $\overline{\mathbf{Y}}_{c}$ is the average tensor of the samples belonging to class $c$;
- $\overline{\mathbf{Y}}$ is the average tensor of all the samples;
- $\overline{\mathbf{Y}}_{c_{i}}$ is the average of the class corresponding to the ith tensor.


## Justification of Fisher criterion for Tensors [Filisbino et al., 2015]

In [Yan et al., 2005] Fisher criterion is implemented by:

$$
\begin{equation*}
\left(\left.U^{j}\right|_{j=1} ^{n}\right)=\arg \max _{\left.U j\right|_{j=1} ^{n}} \frac{\sum_{c=1}^{C} N_{c} \cdot\left\|\overline{\mathbf{X}}_{c} \times_{1} U^{1} \ldots \times_{n} U^{n}-\overline{\mathbf{X}} \times_{1} U^{1} \ldots \times_{n} U^{n}\right\|^{2}}{\sum_{i=1}^{N}\left\|\mathbf{X}_{i} \times \times_{1} U^{1} \ldots \times_{n} U^{n}-\overline{\mathbf{X}}_{c_{i}} \times{ }_{1} U^{1} \ldots \times_{n} U^{n}\right\|^{2}}, \tag{39}
\end{equation*}
$$

We can rewrite expression (39) as:

## Justification for Fisher criterion for Tensors

By considering Frobenius norm:

$$
\begin{equation*}
\left(\left.U^{j}\right|_{j=1} ^{n}\right)=\arg \max _{U i_{j=1}^{n}} \frac{\sum_{j_{1}, j_{2}, \cdots, j_{n}}\left(\sum_{c=1}^{c} N_{c} \cdot\left(\overline{\mathbf{Y}}_{c ; j_{1}, j_{2}, \cdots, j_{n}} \bar{Y}_{j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}\right)}{\sum_{j_{1}, j_{2}, \cdots, j_{n}}\left(\sum_{i=1}^{N}\left(\mathbf{Y}_{i, j_{1}, j_{2}, \cdots, j_{n}} \overline{\mathbf{Y}}_{c_{i, j} j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}\right)}, \tag{41}
\end{equation*}
$$

We can postulate that the larger is the value of $\Gamma_{j_{1}, j_{2}, \cdots, j_{n}}$ computed by:

$$
\begin{equation*}
W_{j_{1}, j_{2}, \cdots, j_{n}}^{F i ; i n e r}=\frac{\sum_{c=1}^{C} N_{c} \cdot\left(\overline{\mathbf{Y}}_{c ; j_{1}, j_{2}, \cdots, j_{n}-} \overline{\mathbf{Y}}_{j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}}{\sum_{i=1}^{N}\left(\mathbf{Y}_{i ; j_{1}, j_{2}, \cdots, j_{n}-} \overline{\mathbf{Y}}_{c_{i} ; j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}}, \tag{42}
\end{equation*}
$$

then more discriminant is the tensor component $\widetilde{\mathbf{e}}_{1}^{j_{1}} \otimes \widetilde{\mathbf{e}}_{2}^{j_{2}} \cdots \otimes \widetilde{\mathbf{e}}_{n}^{j_{n}}$ for samples classification.

## Experimental Results

## Faces Database

Fei Database:



Figure: FEI face database sample. http://fei.edu.br/~cet/facedatabase.html

# Experimental Results: Ranking MPCA/CSA Components. 

## Gender Experiments

Database: $\left(\mathbf{X}_{i}, l_{i}\right) \in \mathbb{R}^{480 \times 640 \times 11}, l_{i} \in\{-1,1\}$


## Implementation Details

## System

- Processor: Intel-Core-I7
- Cores: 6 - Threads: 12
- RAM: 12GB
- $S_{1}=\mathbb{R}^{479 \times 639 \times 11}>12 G B \Rightarrow$ Time $=3 h \Rightarrow T_{\text {max }}=3$
- $S_{2}=\mathbb{R}^{33 \times 42 \times 9}=7 G B \Rightarrow$ Time $=5^{\prime} \Rightarrow T_{\text {max }}=4$


## Implementation Details

- Install the Matlab Tensor Toolbox.
- http://www.sandia.gov/ tgkolda/TensorToolbox/


## Principal Functions

- tensor $(X)$ : transform in tensor the generalize matrix $X$.
- tenmat $(X, n)$ : flattening in dimension $n$.
- $\operatorname{ttm}(X, U, n):$ mode- $k$ product.


## Examples

- tenmat $(\mathbf{X}, 1)$

$\mathbf{X} \in \Re^{m_{1} \times m_{2} \times m_{3}}$

$\mathbf{X}_{(1)} \in \Re_{\Re_{1} \times m_{2} m_{3}}$

$$
X_{(1)}=\left[\begin{array}{lll|lll}
x_{(111)} & x_{(121)} & x_{(131)} & x_{(112)} & x_{(122)} & x_{(132)} \\
x_{(211)} & x_{(221)} & x_{(231)} & x_{(212)} & x_{(222)} & x_{(232)} \\
x_{(311)} & x_{(321)} & x_{(331)} & x_{(312)} & x_{(322)} & x_{(332)}
\end{array}\right]
$$

## Examples

- tenmat $(\mathbf{X}, 2)$

$\mathbf{X} \in \Re^{m_{1} \times m_{2} \times m_{3}}$

$\mathbf{X}_{(2)} \in \Re^{m_{2} \times m_{1} m_{3}}$

$$
X_{(2)}=\left[\begin{array}{lll:lll}
x_{(111)} & x_{(211)} & x_{(311)} & x_{(112)} & x_{(212)} & x_{(312)} \\
x_{(121)} & x_{(221)} & x_{(321)} & x_{(122)} & x_{(222)} & x_{(322)} \\
x_{(131)} & x_{(231)} & x_{331)} & x_{(132)} & x_{(232)} & x_{(332)}
\end{array}\right]
$$

## Examples

- tenmat $(\mathbf{X}, 3)$

$\mathbf{X} \in \Re^{m_{1} \times m_{2} \times m_{3}}$

$\mathbf{X}_{(3)} \in \Re^{m_{3} \times m_{1} m_{2}}$


## Examples

Let the Tensor $\mathbf{X} \in \mathbb{R}^{m_{1} \times m_{2} \times m_{3}}$ and the matrix $U \in \mathbb{R}^{m^{\prime} \times m_{k}}$. The function,

- $\operatorname{ttm}(\mathbf{X}, U, n)=\left(\mathbf{X} \times{ }_{n} A\right)$
$\Rightarrow \operatorname{ttm}(\mathbf{X}, U, 1)=\left(\mathbf{X} \times{ }_{1} U\right)_{m_{1}^{\prime}, m_{2}, m_{3}}=\sum_{j=1}^{m_{1}} \mathbf{X}_{j, m_{2}, m_{3}} \cdot U_{m_{1}^{\prime}, j}$
$\Rightarrow \operatorname{ttm}(\mathbf{X}, U, 2)=\left(\mathbf{X} \times{ }_{2} U\right)_{m_{1}, m_{2}^{\prime}, m_{3}}=\sum_{j=1}^{m_{2}} \mathbf{X}_{m_{2}, j, m_{3}} \cdot U_{m_{2}^{\prime}, j}$
$\Rightarrow \operatorname{ttm}(\mathbf{X}, U, 3)=(\mathbf{X} \times 3 U)_{m_{1}, m_{2}, m_{3}^{\prime}}=\sum_{j=1}^{m_{3}} \mathbf{X}_{m_{1}, m_{2}, j} \cdot U_{m_{3}^{\prime}, j}$
Matricized version
$\mathbf{Y}=\left(\mathbf{X} \times{ }_{n} U\right) \Longleftrightarrow Y_{(n)}=U X_{(n)}$

1: Input: Samples $\left\{\mathbf{X}_{i} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}, i=1, \ldots, N\right\} ; \operatorname{tensor}\left(\mathbf{X}_{i}\right)$
2: Preprocessing: Center the input samples as $\left\{\widetilde{\mathbf{X}}_{i}=\mathbf{X}_{i}-\overline{\mathbf{X}}\right\}$
3: Initialization: Eigen-decomposition of $\Phi^{(k) *}=\sum_{i=1}^{N} \widetilde{\mathbf{X}}_{i(k)} \cdot \widetilde{\mathbf{X}}_{i(k)}^{T}$, set $U_{0}^{k}$ as the most significant $m_{k}^{\prime}$ eigenvectors, for $k=1, \ldots, n . \widetilde{\mathbf{X}}_{i(k)} \longleftarrow \operatorname{tenmat}\left(\widetilde{\mathbf{X}}_{i}, k\right)$
4: Local optimization:
5: Compute $\widetilde{\mathbf{Y}}_{i}=\widetilde{\mathbf{X}}_{i} \times_{1} U_{0}^{1^{\top}} \ldots \times_{n} U_{0}^{n^{\top}}, i=1, \ldots, N ;$ $\mathbf{Y}=\operatorname{ttm}(\widetilde{\mathbf{X}}, U s, 1 . . n)$
6: Compute $\Upsilon_{0}=\sum_{i=1}^{N}\left\|\widetilde{\boldsymbol{Y}}_{i}\right\|_{F}^{2}$;
7: for $t=1, \ldots$ to $T_{\text {max }}$ do
8: $\quad$ for $k=1, \ldots$ to $n$ do
9: $\quad$ Set the matrix $U_{t}^{k}$ to consist of the $m_{k}^{\prime}$ leading eigenvectors of $\Phi^{(k)}$, defined in expression (28);

$$
U_{t}^{k} \longleftarrow \Phi^{k}=A_{(k)} \cdot A_{(k)}^{T} \longleftarrow \operatorname{tenmat}\left(\mathbf{A}^{k}, k\right)=\operatorname{ttm}(\widetilde{\mathbf{X}}, U s,-k)
$$

10: end for
11: Compute $\widetilde{\mathbf{Y}}_{i}, i=1, \ldots, N$ and $\Upsilon_{t}$;
12: if $\left|\Upsilon_{t}-\Upsilon_{t-1}\right|<\eta$ then
13: $\quad$ break; $\eta=0.001$
14: end if
15: end for
16: Output:Projection matrices $U^{k}=U_{t}^{k}, k=1, \ldots, n$.

## Estimating MPCA Subspaces Dimensions

The reduced dimensions $m_{k}^{\prime}, k=1,2, \ldots, n$ must be specified in advance or determined by some heuristic. In [Lu et al., 2008] it is proposed to compute these values in order to satisfy the criterium:

$$
\begin{equation*}
\frac{\sum_{i_{k}=1}^{m_{k}^{\prime}} \lambda_{i_{k}(k)}}{\sum_{i_{k}=1}^{m_{k}} \lambda_{i_{k}(k)}}>\Omega \tag{43}
\end{equation*}
$$

where $\Omega$ is a threshold to be specified by the user and $\lambda_{i_{k}(k)}$ is the $i_{k}$ th eigenvalue of $\Phi^{(k) *}(\Omega=0.95)$.

## CSA Algorihm

1: Input: Samples $\left\{\mathbf{X}_{i} \in \mathbb{R}^{m_{1} \times m_{2} \times \ldots \times m_{n}}, i=1, \ldots, N\right\}$; dimensions $m_{k}^{\prime} ; k=1, \cdots, n$.
2: Initialization of $U_{0}^{k}$ by truncating the number of columns of the identity matrix;
3: for $t=1, \ldots$ to $T_{\max }$ do
4: $\quad$ for $k=1, \ldots$ to $n$ do
5: Mode-k tensor products:

$$
\mathbf{X}_{i}^{k}=\mathbf{X}_{i} \times{ }_{1} U_{t}^{1^{\top}}
$$

Mode-k flattening:
$\mathbf{X}_{i}^{k}$ for the matrix $X_{i}^{k}: X_{i}^{k} \Longleftarrow{ }_{k} \mathbf{X}_{i}^{k}$
Covariance matrix computation:

$$
C^{k}: C^{k}=\sum_{i=1}^{N} X_{i}^{k} X_{i}^{k^{T}}
$$

8: Compute the first $m_{k}^{\prime}$ leading eigenvectors of $C^{k}$, $C^{k} U_{k}^{t}=U_{k}^{t} \Lambda^{k}$, which constitute the column vectors of $U_{k}^{t}$
9: end for
10: if $\left(t>2\right.$ and $\left.\operatorname{Tr}\left[\operatorname{abs}\left(U_{t}^{k^{\top}} U_{t-1}^{k}\right)\right] / m_{k}^{\prime}>(1-\epsilon), k=1, \ldots, n\right)$ then
11: break; $\epsilon=0.001$
12: end if
13: end for
14: Output the matrices $U_{k}=U_{k}^{t}, k=1, \ldots, n$.

## Review: Ranking Tensor Components

- Statistical Variance

$$
\begin{equation*}
E=\left\{\boldsymbol{\Psi}_{j_{1}, j_{2}, \cdots, j_{n}}, j_{k}=1,2, \cdots, m_{k}\right\} \tag{44}
\end{equation*}
$$

- Spectral Structure

$$
\begin{equation*}
E=\left\{\lambda_{j_{1}, j_{2}, \cdots, j_{n}}=\lambda_{j_{1}}^{1} \lambda_{j_{2}}^{2} \cdots \lambda_{j_{n}}^{n}, j_{k}=1,2, \cdots, m_{k}\right\} \tag{45}
\end{equation*}
$$

- Fisher criterion

$$
\begin{equation*}
W_{j_{1}, j_{2}, \cdots, j_{n}}^{\text {Fisher }}=\frac{\sum_{c=1}^{C} N_{c} \cdot\left(\overline{\mathbf{Y}}_{c ; j_{1}, j_{2}, \cdots, j_{n}-} \overline{\mathbf{Y}}_{j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}}{\sum_{i=1}^{N}\left(\mathbf{Y}_{i ; j_{1}, j_{2}, \cdots, j_{n}-} \overline{\mathbf{Y}}_{c_{i} ; j_{1}, j_{2}, \cdots, j_{n}}\right)^{2}} \tag{46}
\end{equation*}
$$

- TDPCA: Largest discriminant weights $\left|w_{1}\right| \geq\left|w_{2}\right| \geq \ldots \geq\left|w_{m}\right|$


## Understanding Tensor Components



Figure: Subspace $S_{1}^{m p c a}$ for FEI database. Ranking using: (a) Statistical variance (horizontal axis), TDPCA-SVM (red) and spectral variance (blue). (b) Including the ranking by Fisher criterion.

## Understanding Tensor Components

In order to quantify the amount of variance of the principal components, the proportion of total variance information $\lambda$ described by the $k^{\text {th }}$ tensor principal component can be calculated as follows:

$$
\begin{equation*}
\lambda_{k}=\frac{\lambda_{k}}{\sum_{j=1}^{m} \lambda_{j}}, \quad k=1,2, \ldots, m=\prod_{i=1}^{n} m^{\prime}, \tag{47}
\end{equation*}
$$

where $\left\{\lambda_{1}, \lambda_{2}, \ldots, \lambda_{m}\right\}$ are the estimated variances.

## Understanding Tensor Components: Total Variance


(a)

(b)

Figure: (a) Amount of total variance explained by the $600 S_{1}^{\text {mpca }}$ most expressive tensor components selected by spectral variance, TDPCA-SVM, and Fisher criteria. (b) Amount of total variance using the 600 most expressive tensor components of $S_{2}^{\text {mpca }}$, including also the TDPCA-MLDA components.

## Understanding Tensor Components

In order to quantify the discriminant power of the principal components, the proportion of total discriminant information $t$ described by the $k^{t h}$ tensor principal component can be calculated as follows:

$$
\begin{equation*}
t_{k}=\frac{\left|\sigma_{k}\right|}{\sum_{j=1}^{m}\left|\sigma_{j}\right|}, \quad k=1,2, \ldots, m \tag{48}
\end{equation*}
$$

where $m$ is the subspace dimension and $\left[\sigma_{1}, \sigma_{2}, \ldots, \sigma_{m}\right]$ are the weights computed using the separating hyperplanes.

## Experimental Results: Total Discriminant



$S_{1}^{m p c a}$

$$
S_{2}^{m p c a}
$$

## Recognition Rates

We have compared the effectiveness of the tensor principal components ranked on recognition tasks using:

- $k$-fold cross validation.
- Computing the Mahalanobis distance from $\mathbf{Y}_{t}$ to $\overline{\mathbf{Y}}_{i}$.

$$
\begin{equation*}
d_{i}^{k}\left(\mathbf{Y}_{t}\right)=\sum_{j=1}^{k} \frac{1}{\lambda_{j}}\left(\mathbf{Y}_{t ; j}-\overline{\mathbf{Y}}_{i ; j}\right)^{2} \tag{49}
\end{equation*}
$$

where, $\widehat{\mathbf{Y}}_{t}$ is test observation and $\overline{\widehat{\mathbf{Y}}}_{i}$ class mean, with $\lambda_{j}$ is the corresponding spectral variance and $k$ is the number of tensor principal components retained.

## Recognition Rates for Gender (FEI Database)



$S_{1}^{m p c a}$

$S_{2}^{m p c a}$


## Projection in subspace $\widehat{B}_{2}$



Figure: $S_{2}^{\text {mpca }}$


Figure: $S_{2}^{m p c a}$


Figure: $S_{2}^{\text {csa }}$


Figure: $S_{2}^{\text {csa }}$

## Reconstruction

The reconstruction error, which is quantified through the root mean squared error (RMSE), computed as follows:

$$
\begin{equation*}
\operatorname{RMSE}(\widehat{B})=\sqrt{\frac{\sum_{i=1}^{N}\left\|\mathbf{X}_{i}^{R}-\mathbf{X}_{i}\right\|^{2}}{N}} \tag{50}
\end{equation*}
$$

where $\widehat{B}$ is the subspace for projection.

## Multidimensional Image Data Representation



## RMSE



## Reconstruction from Subspace $\widehat{B}_{100}$

MPCA:


Fisher
TDPCA-
MLDA
Spectral
TDPCASVM

CSA:


Fisher
TDPCAMLDA


TDPCASVM

## Computational Complexity: Asymptotic Analysis

Assuming $m_{1}=m_{2}=\ldots m_{n}=m$. One iteration of MPCA

- Formation of the matrix $\Phi^{(k)}: O\left(N \cdot n \cdot m^{(n+1)}\right)$,
- Eigen-decomposition: $O\left(m^{3}\right)$
- Computation of projection $\widetilde{\mathbf{Y}}_{i}: O\left(n \cdot m^{(n+1)}\right)$
- Computation Complexity for MPCA: $O\left(N \cdot n \cdot m^{(n+1)}\right)$

Computational Complexity of Ranking Techniques

- Spectral: $O\left(\prod_{i=1}^{n} m^{\prime}{ }_{i}\right)$
- TDPCA-MLDA: $\left.O\left(\min \left(N, \prod_{i=1}^{n} m^{\prime}{ }_{i}\right) \cdot \prod_{i=1}^{n} m^{\prime}\right)\right)$
- TDPCA-SVM: $O\left(\max \left(N, \prod_{i=1}^{n} m \prime_{i}\right) \cdot N^{2}\right)$
- Fisher: $O\left(N \cdot \prod_{i=1}^{n} m^{\prime}\right)$


## Issues in Multilinear Applications

- Issues in Multilinear Applications
- Many problems involving tensors are NP-hard. Ex: Finding the best rank-1 tensor decomposition [Hillar and Lim, 2013];
- A problem $\Pi$ is NP-hard if a polynomial-time algorithm for $\Pi$ would imply a polynomial-time algorithm for every problem in NP. A problem is NP-complete if it is both NP-hard and an element of NP.
- Memory/CPU requirements
- Reconstruction Artifacts
- Tensors in differentiable manifolds
- Incorporating prior information in MPCA


## Perspectives: Manifold Learning and Tensor Fields



Figure: Manifold charting.

## Perspectives: Manifold Learning and Tensor Fields

## $T_{x} M$



Figure: Tangent vector and tangent space.

## Perspectives: Manifold Learning and Tensor Fields

- Tensor field
- Given subspaces $T_{p}^{i}(\mathcal{M}) \subset T_{p}(\mathcal{M})$, with $\operatorname{dim}\left(T_{p}^{i}(\mathcal{M})\right)=m_{i}$, $i=1,2, \cdots, n$,
- The tensor product: $T_{p}^{1}(\mathcal{M}) \otimes T_{p}^{2}(\mathcal{M}) \otimes \cdots \otimes T_{p}^{n}(\mathcal{M})$,
- Individual basis $\left\{\mathbf{e}_{k}^{i_{k}}(p), i_{k}=1,2, \cdots, m_{k}\right\} \subset T_{p}^{k}(\mathcal{M})$;
- A basis for the vector space $T_{p}^{1}(\mathcal{M}) \otimes T_{p}^{2}(\mathcal{M}) \otimes \cdots \otimes T_{p}^{n}(\mathcal{M})$ is the set:

$$
\begin{equation*}
\left\{\mathbf{e}_{1}^{i_{1}}(p) \otimes \mathbf{e}_{2}^{i_{2}}(p) \otimes \cdots \otimes \mathbf{e}_{n}^{i_{n}}(p), \quad \mathbf{e}_{k}^{i_{k}}(p) \in T_{p}^{k}(\mathcal{M})\right\} \tag{51}
\end{equation*}
$$

- A tensor $\mathbf{X}$ of order $n$ in $p \in \mathcal{M}$ :

$$
\begin{equation*}
\mathbf{X}(p)=\sum_{i_{1}, i_{2}, \cdots, i_{n}} \mathbf{X}_{i_{1}, i_{2}, \cdots, i_{n}}(p) \mathbf{e}_{1}^{i_{1}}(p) \otimes \mathbf{e}_{2}^{i_{2}}(p) \otimes \cdots \otimes \mathbf{e}_{n}^{i_{n}}(p) . \tag{52}
\end{equation*}
$$

## Perspectives: Manifold Learning and Tensor Fields

The application of the above concepts for data analysis depends on the following issues:

- Manifold learning to build the local coordinate systems $\left\{\left(U_{\alpha}, \varphi_{\alpha}\right)\right\}_{\alpha \in I}$, for $\mathcal{M}$;
- Discrete tensor field computation $\mathbf{X}\left(p_{i}\right), i=1,2, \cdots, N$;
- Local subspace learning technique to perform dimensionality reduction to compute the discrete tensor field $\mathbf{Y}\left(p_{i}\right), i=1,2, \cdots, N$, given by:

$$
\begin{equation*}
\mathbf{Y}\left(p_{i}\right)=\left(\mathbf{X} \times 1 \mathbf{U}^{1^{T}} \times_{2} \mathbf{U}^{2^{T}} \ldots \times_{n} \mathbf{U}^{n^{T}}\right)\left(p_{i}\right) \tag{53}
\end{equation*}
$$

Perspectives: Application of Spatial Weighting Maps

Leonardo da Vinci's Advice to Artists (E. Kelen, 1990)

- "If Nature had a fixed model for the proportions of the face everyone would look alike and it would be impossible to tell them apart; but she has varied the pattern in such a way that although there is an all but universal standard as to size, one clearly distinguishes one face from another."
$\rightarrow$ Holistic cognition task composed of configural (global) and featural (local) sources of information.


## Is the frontal face below of a male subject?



## Is the frontal face below of a male subject?



## Is the frontal face below of a male subject?



## Yes. It is a male.



Priori information (from left to right): Statistical, cognitive and both.


## How do we accomplish this process of coding and decoding faces?

We will present a feature extraction approach of determining priori-driven dimensions along which face images vary that might be useful to understand the way faces are processed.

Goal:Combine variance with prior knowledge and analyze all features simultaneously.

## Geometric idea:



## Geometric idea: (cont.)



## Geometric idea: (cont.)



## Geometric idea: (cont.)



## Mathematically,

Let an $N \times n$ data matrix $X$ be composed of $N$ face images with $n$ pixels, that is, $X=\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{N}\right)^{T}$. Let this data matrix $X$ have covariance matrix

$$
S=\frac{1}{(N-1)} \sum_{i=1}^{N}\left(\mathbf{x}_{i}-\overline{\mathbf{x}}\right)\left(\mathbf{x}_{i}-\overline{\mathbf{x}}\right)^{T},
$$

where $\overline{\mathbf{x}}$ is the grand mean vector of $X$ given by

$$
\overline{\mathbf{x}}=\frac{1}{N} \sum_{i=1}^{N} \mathbf{x}_{i}=\left(\bar{x}_{1}, \bar{x}_{2}, \ldots, \bar{x}_{n}\right)
$$

## Mathematically, (cont.)

Let an $N \times n$ data matrix $X$ be composed of $N$ face images with $n$ pixels, that is, $X=\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{N}\right)^{T}$. Let this data matrix $X$ have covariance matrix

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where $\overline{\mathbf{x}}$ is the grand mean vector of $X$ given by

$$
\overline{\mathbf{x}}=\frac{1}{N} \sum_{i=1}^{N} \mathbf{x}_{i}=\left(\bar{x}_{1}, \bar{x}_{2}, \ldots, \bar{x}_{n}\right)
$$

$\rightarrow$ Variable deviations from the mean have the same weight. That is, all the $n$ variables are equally important.

## Mathematically, (cont.)

The well-known Pearson's sample correlation coefficient between the $j^{\text {th }}$ and $k^{\text {th }}$ pixels can be defined as follows:

$$
\begin{aligned}
r_{j k} & =\frac{s_{j k}}{\sqrt{s_{j}} \sqrt{s_{k}}} \\
& =\frac{\sum_{i=1}^{N}\left(x_{i j}-\bar{x}_{j}\right)\left(x_{i k}-\bar{x}_{k}\right)}{\sqrt{\sum_{i=1}^{N}\left(x_{i j}-\bar{x}_{j}\right)^{2}} \sqrt{\sum_{i=1}^{N}\left(x_{i k}-\bar{x}_{k}\right)^{2}}}
\end{aligned}
$$

for $j=1,2, \ldots, n$ and $k=1,2, \ldots, n$. Analogously we can describe a priori-driven sample covariance $s_{j k}^{*}$ between the $j^{t h}$ and $k^{t h}$ variables by

$$
\begin{aligned}
s_{j k}^{*} & =\left(\sqrt{w_{j}} \sqrt{w_{k}}\right) s_{j k} \\
& =\sum_{i=1}^{N} \sqrt{w_{j}}\left(x_{i j}-\bar{x}_{j}\right) \sqrt{w_{k}}\left(x_{i k}-\bar{x}_{k}\right) .
\end{aligned}
$$

## Mathematically, (cont.)

The spatial weighting vector (or spatial attention map)

$$
\mathbf{w}=\left[w_{1}, w_{2}, \ldots, w_{n}\right]^{T}
$$

is such that $w_{j} \geq 0$ and $\sum_{j=1}^{n} w_{j}=1$, where each $w_{j}$ measures the information power of the $j^{\text {th }}$ pixel. Thus, when $n$ pixels are observed on $N$ samples, the weighted sample covariance matrix $S^{*}$ can be described by

$$
S^{*}=\left\{s_{j k}^{*}\right\}=\left\{\sum_{i=1}^{N} \sqrt{w_{j}}\left(x_{i j}-\bar{x}_{j}\right) \sqrt{w_{k}}\left(x_{i k}-\bar{x}_{k}\right)\right\}
$$

Mathematically, (cont.)

Let $S^{*}$ have respectively $P^{*}$ and $\Lambda^{*}$ eigenvector and eigenvalue matrices, as follows:

$$
P^{* T} S^{*} P^{*}=\Lambda^{*} .
$$

The set of $m(m \leq n)$ eigenvectors of $S^{*}$, that is,

$$
P^{*}=\left[\mathbf{p}_{1}^{*}, \mathbf{p}_{2}^{*}, \ldots, \mathbf{p}_{m}^{*}\right]
$$

which corresponds to the $\underline{m}$ largest eigenvalues, defines the orthonormal coordinate system for the data matrix $X$ called priori-driven principal components.

## Incorporating priori-driven information (algorithm)

 Spatially weighted PCA(1) Calculate a spatial weighting vector $\mathbf{w}=\left[w_{1}, w_{2}, \ldots, w_{n}\right]^{T}$;
(2) Normalize w: Replace $w_{j}$ with $\frac{\left|w_{j}\right|}{\sum_{j=1}^{n}\left|w_{j}\right|}$;
(3) Standardize all $n$ variables, replacing $x_{i j}$ with $z_{i j}=x_{i j}-\bar{x}_{j}$;
(9) Spatially weigh up all the standardized $z_{i j}: z_{i j}^{*}=z_{i j} \sqrt{w_{j}}$;
(5) Calculate $P^{*}$, the $m$ largest eigenvectors of $\left(Z^{*}\right)^{T} Z^{*}$.

## Experiments

Two-group separation tasks (frontal faces):

- Gender (female versus male)
- Facial expression (smiling versus non-smiling)

Database (2D): FEI (400 images, 200 subjects)

Note: All the face images have been converted to grayscale, pre-aligned and cropped to $128 \times 128$ pixels in size.

## Experiments (cont.)

Statistical prior information has been described simply by the leading eigenvector of the between-scatter matrix $S_{b}$

$$
S_{b}=\sum_{i=1}^{g} N_{i}\left(\overline{\mathbf{x}}_{i}-\overline{\mathbf{x}}\right)\left(\overline{\mathbf{x}}_{i}-\overline{\mathbf{x}}\right)^{T}
$$

$\rightarrow$ 1st order statistical differences.

## Experiments (cont.)

Cognitive prior information has been described by (absolute) gaze duration heatmap means using Tobii TX300 eye tracker and the following settings:

- Binocular tracking
- Data sampling rate of 300 Hz
- Minimum fixation duration of 60 ms
- Maximum dispersion threshold of 0.5 degrees

Each stimulus task begins with a calibration procedure implemented in the Tobii Studio software to ensure accurate tracking of the eye gaze.

## Experiments (cont.)

Stimuli composed of 60 images distributed equally among the tasks with the following display settings:

- Face images enlarged to $512 \times 512$ pixels
- Black background and stimuli centralized
- Central fixation cross in between stimuli
- Presentation at a distance of 60 cm
- 23in 1920x1080 widescreen monitor

All face stimuli are presented for 3 seconds followed by a question that requires a response in relation to the task (male/female, smiling/non-smiling).

## Experiments (cont.)

A number of 44 adults ( 26 men and 18 women) participated in these experiments. All participants:

- are Brazilian students or staff at FEl
- have normal or correct vision
- provided written informed consent
- Presentation at a distance of 60 cm


## Gender experiments/results (gazeplot, 3 seconds)



## Facial expression experiments/results (gazeplot, 3 seconds)



## Gender and facial expression corresponding heatmaps



## Results (statistical prior information)



Note: Differences are essentially local.

## Results (cognitive prior information)



Note: Differences are essentially global.

## Results (both prior information)




Note: Global and local differences.

## Results (dimensionality reduction)




Note: Less priori-driven components than standard ones.

## Results (inner product matrices of the top 20 components)



Note: Changes in the information retained and the ordering of pcas.

## Results (10-fold cross validation, nearest neighbor)




Note: Cognitive prior information alone disappointing. But if combined with statistical one could improve the discriminant power of the components.

Thus,

## How do we accomplish this process of coding and decoding faces?

"... it is not really the perception of likeness for which we are originally programmed, but the noticing of unlikeness, the departure from the norm which stands out and sticks in the mind." (Grombrich, E. H., 1972)
$\rightarrow$ Priori-driven variance might be a way forward.

## Perspectives: High Performance and NN-Factoring

- High Performance Solutions:
- Reduce the inter processor communication in distributed memory algorithms [Austin et al., 2015],
- Intermediate data explosion: computation of matrix $\Phi^{(k)}$, fast memory access in mode-k flattening
- Out-of-Core solutions [Suter et al., 2011]
- Quantum Computers: Could they be effective for tensor problems [Hillar and Lim, 2013]?
- Visualization Artifacts: Non-Negative factorization


## Conclusions and Final Remarks

- Tensor in pattern recognition:
- Dimensionality reduction,
- Ranking tensor components
- Classification
- Reconstruction
- Generalized Matrix and Tensor Product Approaches
- Tensor computation is not matrix computation with additional subscripts
- Tensors are geometric objects
- Manifold learning
- Incorporation of prior knowledge to steer the data mining tasks
- High Performance Requirements

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