

An approach for Brazilian Sign Language (BSL) recognition based on facial expression and k-NN classifier

Tamires Martins Rezende¹

Cristiano Leite de Castro¹

Sílvia Grasiella Moreira Almeida²

¹The Electrical Engineering Graduate Program - UFMG

²Department of Industrial Automation - IFMG Ouro Preto.

Summary

- 1 Brazilian Sign Language
- 2 Database
- 3 Methodology and Results
- 4 Conclusions
- 5 Acknowledgment

Brazilian Sign Language (BSL) or Libras

- The second official language of Brazil.
- 5 main parameters:
 - 1 point of articulation,
 - 2 hand configuration,
 - 3 movement,
 - 4 palm orientation and
 - 5 non-manual expressions.
- This paper did an exploratory study of the peculiarities involved in non-manual sign language expression recognition.

Brazilian Sign Language (BSL) or Libras

The BSL recognition using computational methods is a challenge for a variety of reasons:

- There is currently no standardized database containing signs in a format that allows computer classification systems validation;
- One sign is composed of simultaneous elements;
- The language does not contain a consistent identifier for the start and end of a sign;
- Different people complete any given gesture differently.

The Brazilian Sign Language Database

The first step was to choose the signs that contained changes in facial expression during execution.

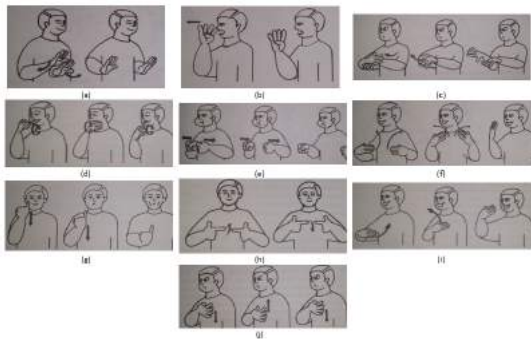


Figure: Signs: (a) to calm down, (b) to accuse, (c) to annihilate, (d) to love, (e) to gain weight, (f) happiness, (g) slim, (h) lucky, (i) surprise, and (j) angry

Record Protocol

After first step to record, the signs were recorded.

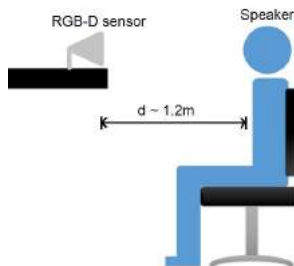


Figure: Scenario created for record the signs

With the 10 signs each recorded 10 times with the same speaker, the balanced database had a total of 100 samples.

Record Protocol

RGB-D sensor \Rightarrow Kinect

Software \Rightarrow nuiCaptureAnalyse

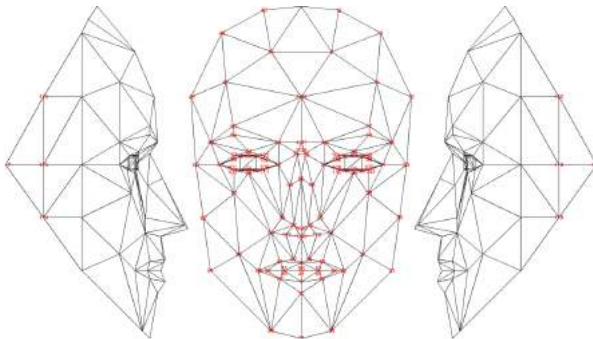


Figure: Facial model used with labeled points

Methodology

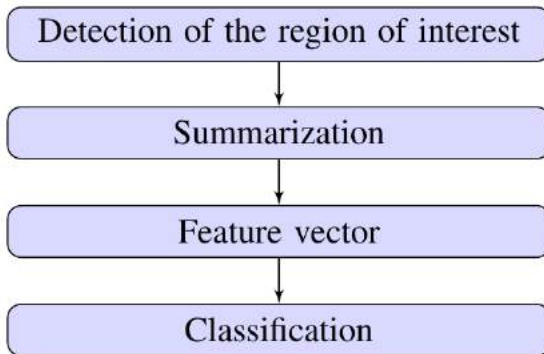


Figure: Methodology for the automatic face recognition system

Step 1: Detection of the region of interest

Input: Signals recorded by Kinect.

Output: Video with the face images.



Figure: Full frame



Figure: Selected face

Step 2: Summarization

Input: Face images.

Output: 5 most relevant frames.



Figure: The five most relevant frames extracted from a recording of the sign “to love”

Step 3: Feature vector

Input: 5 most relevant frames.

Output: Descriptor of a sign.

Descriptor of a single frame:

$$D = [x_1 \ y_1 \ x_2 \ y_2 \ \dots \ x_{121} \ y_{121}]_{1 \times 242}$$

Sign:

$$Vector = [D_1 \ D_2 \ D_3 \ D_4 \ D_5]_{1 \times 1210}$$

$$Vector = [x_{1,1} \ y_{1,1} \ \dots \ x_{i,j} \ y_{i,j} \ \dots \ x_{5,121} \ y_{5,121}]_{1 \times 1210}$$

i = number of the frame and

j = point of the face

Step 4: Classification

Input: Descriptor of a sign.

Output: Average accuracy of the 10 iterations.

Algorithm 1: K-NN CLASSIFICATION

Input: Sign samples
Output: acc_{avg} and σ of the 10 iterations

```

1 Start
2   for  $w = 1$  to 10 do
3     Randomizes the samples of each sign
4      $train \leftarrow$  80% of the data
5      $test \leftarrow$  20% of the data
6     for  $k = 1$  to 10 do
7        $testV \leftarrow$  CROSS-VALIDATION(5-fold)
8        $acc(k) \leftarrow$  K-NN( $testV, k$ )
9     end
10     $[acc\ ind] \leftarrow$   $max(acc)$ 
11     $k_{best} \leftarrow$   $ind$ 
12     $acc_{test}(w) \leftarrow$  K-NN( $test, k_{best}$ )
13  end
14   $acc_{avg} \leftarrow$   $mean(acc_{test}(w))$ 
15   $\sigma \leftarrow$   $std(acc_{test}(w))$ 
16 end
17 return  $acc_{avg}, \sigma$ 

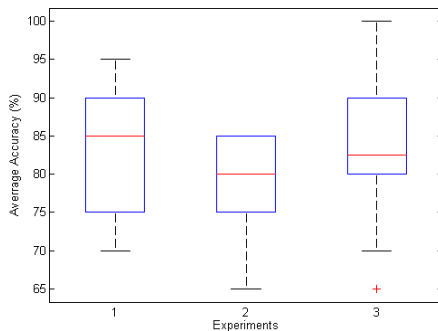
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Experiments and Results

EX1: Raw data.

EX2: Z-Score Normalization.

EX3: Centroid normalization.



Conclusions

- The BSL recognition is a challenge problem.
- The lack of a database well structured with signs in BSL.
- This paper did an exploratory study of the peculiarities involved in non-manual expressions.
- The methodology adopted had a considerable performance, achieving a maximum average accuracy of 84%.

Acknowledgment

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Thank you!